

Multi-Channel Acquisition Module for EMG Signals

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- 3 The Acquisition System
- 4 The Software
- 5 Experimental Setup
- 6 Experimental Results
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Overview



Overview

Motivation

- Electromyography - means of human-computer interaction
- Surface EMG - Easy to implement
- 2 types of sensors tested
- Custom Acquisition Module vs Commercial Device



The EMG Signal



EMG Signal Properties

Typical Characteristics

- Random nature [1];
- Max peak-to-peak amplitude: 10mV [2];
- Bandwidth: [50 - 150] Hz;
- Minimum Sampling Rate: 250 Sa/s [2];
- Subjective [1];
- Noise Sensitive;

Types of EMG Sensors

- Invasive - (not covered);
- Non-Invasive, based on:
 - Gel Electrodes;
 - Dry Electrodes;



The Acquisition System



The Acquisition Chain

It is based on:

- 1 Dry EMG Sensors
- 2 Acquisition Module
- 3 Wireless Adapter
- 4 PC Software

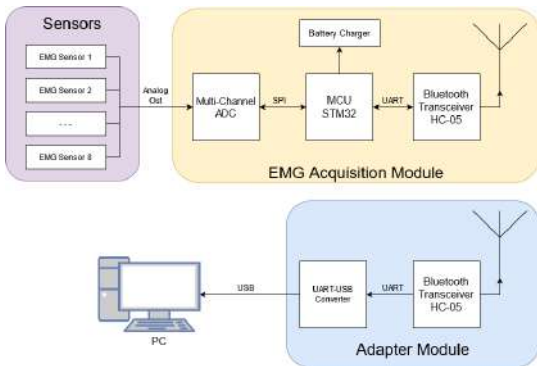


Figure: 1. The Complete Acquisition Chain



Dry EMG Sensors

OyMotion Gravity [3]:

- Metal Dry Electrode;
- Preamplifier Circuit Included;
- Detection Range: $\pm 1.5\text{mV}$;
- Gain: 1000;
- Signal Level: 0 – 3V;
- Signal Offset: 1.5V;
- Typical Bandwidth: 20 – 300Hz;
- Working DC Voltage: 3.3 – 5V;
- Working DC Current: 0.5mA;



Figure: 2. Gravity EMG Sensor (Source: DFRobot).



The Acquisition Module

The Prototype:

- 1 A/D Converter
- 2 Microcontroller
- 3 Transceiver



The Acquisition Module

A/D Converter - AD7124-8 [4]

- Sigma Delta Architecture;
- Max 19200Sa/s;
- 24 bit Conversion (16 bit Used);
- Up to 8 Channels (4 used);
- Sequential Converter;
- Input CrossBar Multiplexer;
- Internal 2.5v Reference;
- 3.3V Digital I/O Operation;
- 0 - 2.5V Analog Input Range;
- SPI Mode 3.
- 1 MHz SPI Clock (For Lower Latency).



Figure: 3. The A/D Converter (Source: Analog Devices).



The Acquisition Module

Microcontroller - STM32 [5]

- 32 bit ARM Cortex M4;
- Optimized for Low Power;
- 256kB Flash/ 64kB RAM;
- 26 I/O, 5V tolerant;
- 3.3V Device;
- High Speed Internal (HSI) 32MHz Clock;



Figure: 4. The Microcontroller (CubeMX Utility View).



The Acquisition Module

Bluetooth Transceiver – HC-05 [6]

- Bluetooth 2.0 Technology;
- 3.5 - 5V Supply;
- Current Draw: 35 – 40mA;
- Transparent Communication via UART;
- Configurable in AT Mode;
- Max UART Baud Rate: 921600bps ;
- 8 Data Bits, 1 Stop Bit, No parity



Figure: 5. HC-05 Module (Source: components101.com).

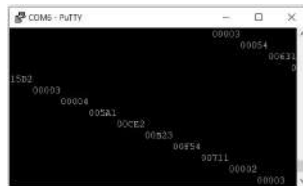


Figure: 6. Sample Stream through UART.



The Adapter

Adapter consists of:

- 1 Bluetooth Transceiver
- 2 UART-USB Converter



Figure: 7. Adapter Module



The Electrical Diagram

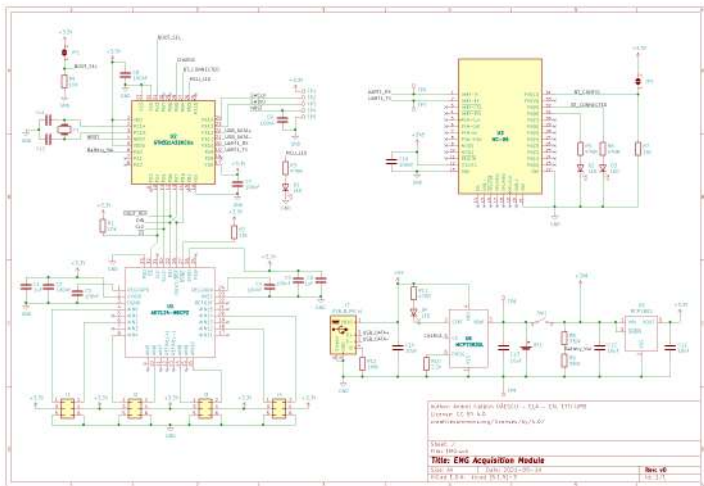


Figure: 8. Complete Electrical Diagram



The PCB

PCB Characteristics:

- Dimensions: 62 × 22 mm;
- FR4 Substrate, 0.8mm Thickness;
- 2 oz Copper, 2 Layers;
- ENIG Copper Finish;

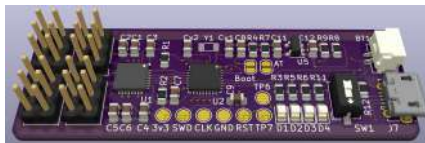


Figure 9. 3D Model of Prototype

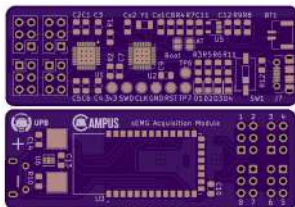


Figure 10. OSHPark PCB



Figure 11. Assembled Prototype



The Software



The Firmware

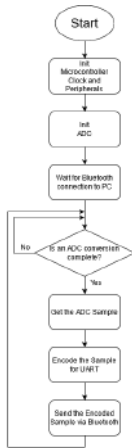


Figure: 12. Software Execution Flowchart

Firmware Characteristics:

- Embedded C;
- Low Level Framework used;
- 7.21 kB Flash with CMSIS;
- 1.53 kB RAM

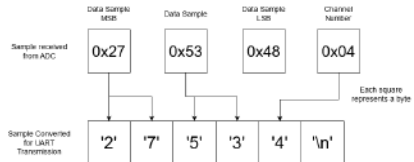


Figure: 13. UART Sample Encoding

1

¹CMSIS = Common Microcontroller Software Interface Standard



The PC Program

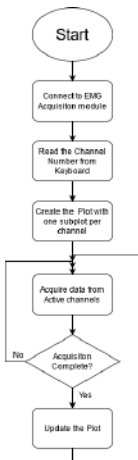


Figure: 14. Software Execution Flowchart

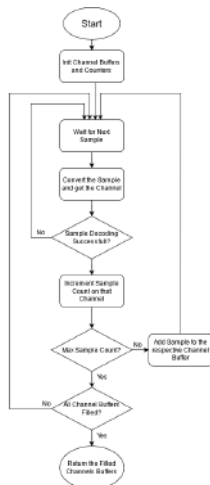


Figure: 15. Reception and Decoding Subroutine



Experimental Setup



OpenBCI

Characteristics		
Device	OpenBCI Cyton [7]	Prototype
Biopotential type	EEG, EMG, ECG	EMG
No. of Channels used	4	4
ADC Type	Sigma Delta	Sigma Delta
Precision (bits)	24	16
Conversion Type	Simultaneous	Sequential
Sample Rate (Sa/s)	250	360
Wireless	Yes	Yes
Easy to equip	No	Yes



Figure: 16. Prototype Setup

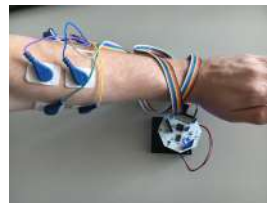


Figure: 17. OpenBCI Setup



Hand Gestures



Figure: 18. Resting Hand



Figure: 29. Wrist Extension



Figure: 20. Wrist Flexion



Figure: 21. Open Hand



Figure: 22. Fist



Figure: 23. Pronation



Figure: 24. Supination



Experimental Results



Time Domain Waveforms

Resting Hand

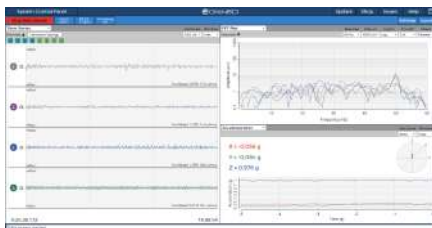


Figure: 25. Cyton Plot

Sampling Rate: 250Sa/s
 Amplitude Scale: $\pm 400\mu\text{V}$
 Time Scale: 5s
 Noise Level: $17.7\mu\text{Vrms}$

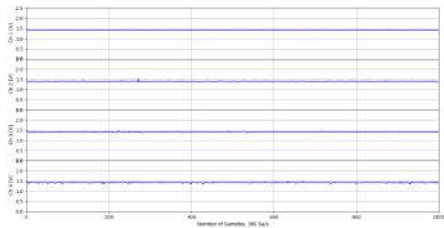


Figure: 26. Prototype Plot

Sampling Rate: 360Sa/s
 Amplitude Scale: 0 – 2.5V
 Time Scale: 2.5s
 Noise Level: $17.7\mu\text{Vrms}$ (x1000 Gain)



Time Domain Waveforms

Wrist Extension

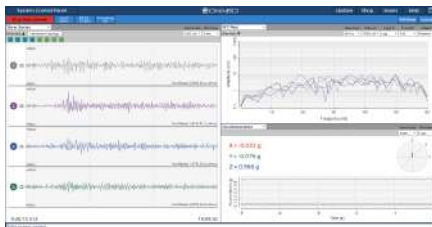


Figure: 27. Cyton Plot

Sampling Rate: 250Sa/s
 Amplitude Scale: $\pm 400\mu\text{V}$
 Time Scale: 5s
 Noise Level: $17.7\mu\text{Vrms}$

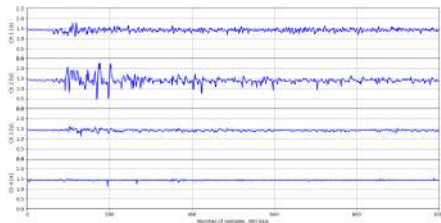


Figure: 28. Prototype Plot

Sampling Rate: 360Sa/s
 Amplitude Scale: 0 – 2.5V
 Time Scale: 2.5s
 Noise Level: $17.7\mu\text{Vrms}$ (x1000 Gain)



Time Domain Waveforms

Wrist Flexion

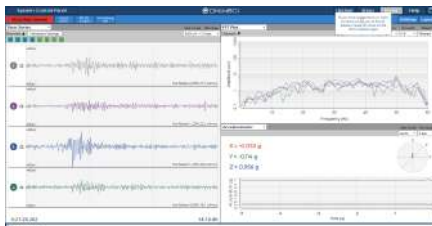


Figure: 29. Cyton Plot

Sampling Rate: 250Sa/s
 Amplitude Scale: $\pm 400\mu\text{V}$
 Time Scale: 5s
 Noise Level: $17.7\mu\text{Vrms}$

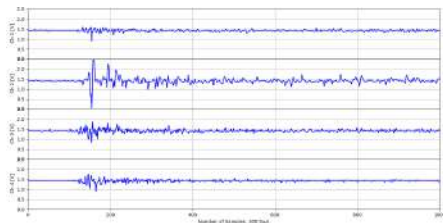


Figure: 30. Prototype Plot

Sampling Rate: 360Sa/s
 Amplitude Scale: 0 – 2.5V
 Time Scale: 2.5s
 Noise Level: $17.7\mu\text{Vrms}$ (x1000 Gain)



Time Domain Waveforms

Open Hand

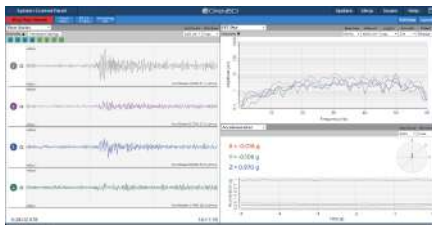


Figure: 31. Cyton Plot

Sampling Rate: 250Sa/s
Amplitude Scale: +/- 400uV
Time Scale: 5s
Noise Level: 17.7uVrms

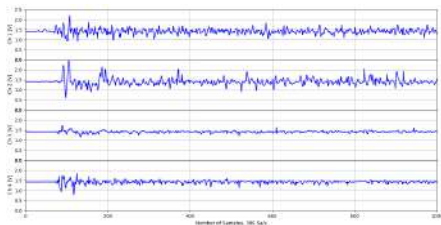


Figure: 32. Prototype Plot

Sampling Rate: 360Sa/s
Amplitude Scale: 0 – 2.5V
Time Scale: 2.5s
Noise Level: 17.7uVrms (x1000 Gain)



Time Domain Waveforms

Fist

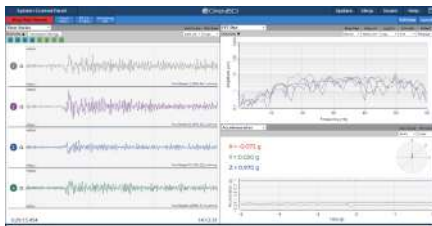


Figure: 33. Cyton Plot

Sampling Rate: 250Sa/s
Amplitude Scale: $\pm 400\mu\text{V}$
Time Scale: 5s
Noise Level: $17.7\mu\text{Vrms}$

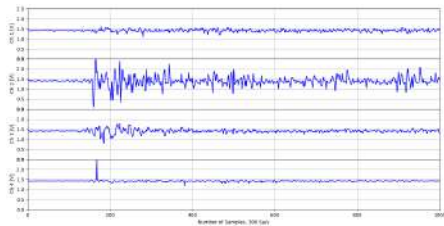


Figure: 34. Prototype Plot

Sampling Rate: 360Sa/s
Amplitude Scale: 0 – 2.5V
Time Scale: 2.5s
Noise Level: $17.7\mu\text{Vrms}$ (x1000 Gain)



Time Domain Waveforms

Pronation

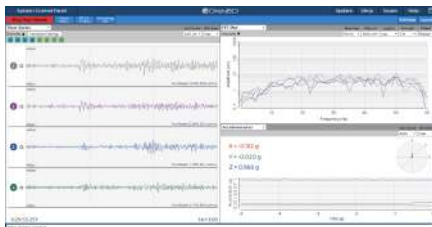


Figure: 35. Cyton Plot

Sampling Rate: 250Sa/s
Amplitude Scale: $\pm 400\mu\text{V}$
Time Scale: 5s
Noise Level: $17.7\mu\text{Vrms}$

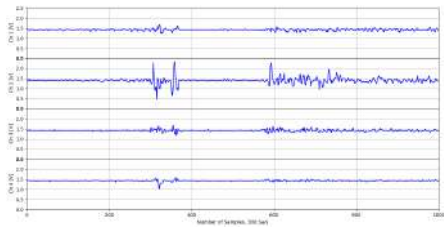


Figure: 36. Prototype Plot

Sampling Rate: 360Sa/s
Amplitude Scale: 0 – 2.5V
Time Scale: 2.5s
Noise Level: $17.7\mu\text{Vrms}$ (x1000 Gain)



Time Domain Waveforms

Supination

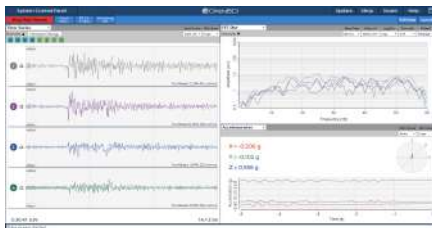


Figure: 37. Cyton Plot

Sampling Rate: 250Sa/s
 Amplitude Scale: $\pm 400\mu\text{V}$
 Time Scale: 5s
 Noise Level: $17.7\mu\text{Vrms}$

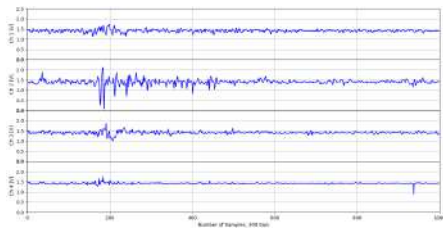


Figure: 38. Prototype Plot

Sampling Rate: 360Sa/s
 Amplitude Scale: 0 – 2.5V
 Time Scale: 2.5s
 Noise Level: $17.7\mu\text{Vrms}$ (x1000 Gain)



Conclusions



Conclusions

Project Conclusions

- Gestures are difficult to replicate;
- Sensor Positioning is Critical;
- Dry Sensors are comparable to Gelled Equivalent;

Contributions

- Designing and building the acquisition chain;
- Designing a wearable module;
- Comparing the types of sensors;

Further Improvements

- Replace MCU and Bluetooth with Wireless SoC;
- DMA communication on Acquisition Device;
- Multiprocessing in PC program;



References

- 1 Jeffrey R Cram and Glenn S Kasman. The basics of surface electromyography. to Surface Electromyography, 1998;
- 2 Ioana Bădițoiu. Electrofiziologie – digitalizarea și prelucrarea semnalelor EMG asociate. 2020;
- 3 <https://www.dfrobot.com/product-1661.html>, 2020;
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- 6 <https://components101.com/wireless/hc-05-bluetooth-module>, 2019;
- 7 <https://docs.openbci.com/docs/Welcome.html>, 2019.



Thank You for Attention!
Questions?

